MULTIDIMENSIONAL INTEGRATION VIA TRAPEZOIDAL AND THREE POINT GENERATORS

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Abstract. Multidimensional integrals are expressed in terms of lower dimensional integrals and function evaluations. An iterative process is used where a trapezoidal and three point identities are used as generators for higher dimensional identities. Bounds are obtained utilising the resulting identities. It is demonstrated that earlier Ostrowski type results are obtained as particular instances of the current work.

1. Introduction

We firstly present one-dimensional identities which may be used as generators for higher dimensional results.

For \( f : [a, b] \rightarrow \mathbb{R} \) we define the Ostrowski and Trapezoidal functionals by

\[
S(f; c, x, d) := f(x) - \mathcal{M}(f; c, d)
\]

and

\[
T(f; c, x, d) := \left( \frac{x - c}{d - c} \right) f(c) + \left( \frac{d - x}{d - c} \right) f(d) - \mathcal{M}(f; c, d),
\]

respectively, where

\[
\mathcal{M}(f; c, d) := \frac{1}{d - c} \int_{c}^{d} f(u) \, du,
\]

the integral mean.

We note that

\[
(b - a) S\left(f; a, \frac{a + b}{2}, b\right) = (b - a) f\left(\frac{a + b}{2}\right) - \int_{a}^{b} f(u) \, du
\]

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and
\[(b - a) T \left( f; a, \frac{a + b}{2}, b \right) = \frac{b - a}{2} \left[ f(a) + f(b) \right] - \int_a^b f(u) \, du, \]
recapturing the midpoint and trapezoidal rules for the evaluation of the integrals. With this in mind, the most common task is to obtain bounds on the above functionals. This task is perhaps best accomplished from identities involving the functionals. The following identities may be easily shown to hold for \( f \) of bounded variation, by an integration by parts argument of the Riemann-Stieltjes integrals and so
\[(1.6)\]
\[ S(f; c, x, d) = \int_c^d p(x, t, c, d) \, df(t), \quad p(x, t, c, d) = \begin{cases} \frac{t - c}{d - c}, & t \in [c, x] \\ \frac{t - d}{d - c}, & t \in (x, d] \end{cases} \]
and
\[(1.7)\]
\[ T(f; c, x, d) = \int_c^d q(x, t, c, d) \, df(t), \quad q(x, t, c, d) = \frac{t - c}{d - c}, \quad x, t \in [c, d]. \]

The book [15] is devoted to Ostrowski type results involving (1.1) and numerous generalisations. See also [1], [16], [19] and [21].

Further, define the three point functional \( \mathcal{S}(f; a, \alpha, x, \beta, b) \) which involves the difference between the integral mean and, a weighted combination of a function evaluated at the end points and an interior point. Namely, for \( a \leq \alpha < x < \beta \leq b, \)
\[(1.8)\]
\[ \mathcal{S}(f; a, \alpha, x, \beta, b) := \left( \frac{\alpha - a}{b - a} \right) f(a) + \left( \frac{\beta - \alpha}{b - a} \right) f(x) + \left( \frac{b - \beta}{b - a} \right) f(b) - \mathcal{M}(f; a, b). \]

Cerone and Dragomir [7] showed that for \( f \) of bounded variation, the identity
\[(1.9)\]
\[ T(f; a, \alpha, x, \beta, b) = \int_a^b r(x, t) \, df(t), \quad r(x, t) = \begin{cases} \frac{t - \alpha}{b - a}, & t \in [a, x] \\ \frac{t - \beta}{b - a}, & t \in (x, b] \end{cases} \]
is valid. They effectively demonstrated that the Ostrowski functional and the trapezoid functional could be recaptured as particular instances.
Specifically, from (1.8) and (1.9)
\[
S(f; a, x, b) = T(f; a, a, x, b, b)
\]
and
\[
T(f; a, x, b) = T(f; a, x, x, x, b)
\]
where \(S(f; a, x, b)\) and \(T(f; a, x, b)\) are defined by (1.1) and (1.2) and satisfy identities (1.6) and (1.7) respectively.

It should be noted at this stage that
\[
(b - a) T\left(f; \frac{5a + b}{6}, \frac{a + b}{2}, \frac{a + 5b}{6}, b\right)
= \frac{b - a}{6} \left[ f(a) + 4f\left(\frac{a + b}{2}\right) + f(b) \right] - \int_a^b f(x) \, dx
\]
is the Simpson functional.

Further, if \(f(t)\) is assumed to be absolutely continuous for \(t \) over its respective interval, then \(df(t) = f'(t) \, dt\) and the Riemann-Stieltjes integrals in (1.8) and (1.9) are equivalent to Riemann integrals. Pachpatte [22] obtains, with the following notation, a trapezoidal type result for double integrals.

He lets \(R\) denote the set of real numbers and \(R^+ = [0, \infty)\) and uses the notation \(\Delta = [a, b] \times [c, d]\) for \(a, b, c, d \in R^+\). If \(f(x, y)\) is a differentiable function defined on \(\Delta\), then its partial derivatives are denoted by \(D_1 f(x, y) = \frac{\partial}{\partial x} f(x, y)\), \(D_2 f(x, y) = \frac{\partial}{\partial y} f(x, y)\), \(D_2 D_1 f(x, y) = \frac{\partial^2}{\partial y \partial x} f(x, y)\). He denotes by \(F(\Delta)\) the class of continuous functions \(f : \Delta \to \mathbb{R}\) for which \(D_1 f(x, y), D_2 f(x, y), D_2 D_1 f(x, y)\) exist and are continuous on \(\Delta\).

**Theorem 1.** If \(f \in F(\Delta)\), then

\[
(1.10) \quad \left| \int_a^b \int_c^d f(s, t) \, dt \, ds - \frac{1}{2} \left( (d - c) \int_a^b [f(s, c) + f(s, d)] \, ds \right. \right.
\]
\[
+ \left( b - a \right) \int_c^d \left[ f(a, t) + f(b, t) \right] \, dt \left. \right]
\]
\[
+ \frac{1}{4} \left( b - a \right) (d - c) \left[ f(a, c) + f(a, d) + f(b, c) + f(b, d) \right] \right| \leq \frac{1}{4} \left( b - a \right) (d - c) \int_a^b \int_c^d |D_2 D_1 f(s, t)| \, dt \, ds.
\]

Using a similar argument, Pachpatte [23] obtains a trapezoidal type result for a triple integral involving function evaluation on the boundary,
single integrals and double integrals. The error is again as in (1.10) obtained only for the first partial derivatives over $\Delta \in L_1[\Delta]$.

In the current work, the generalised trapezoidal and three point identities (1.6)-(1.7) and (1.8)-(1.9) for absolutely continuous functions are used as generators to produce identities involving multidimensional integrals in terms of lower dimensional integrals and function evaluations. These are used to procure bounds for $\frac{\partial^{n} f}{\partial t_{i_{1}} \cdots \partial t_{i_{r}}} \in L^p[I^n], 1 \leq p \leq \infty$, where $I^n = [a_1, b_1] \times \cdots \times [a_n, b_n]$. Here for $h : I^n \to \mathbb{R}$ we mean by $h \in L^p[I^n]$ the Lebesgue norms, that is,

$$
\|h\|_p := \left( \int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} |h(t_1, t_2, \ldots, t_n)|^p \, dt_1 \cdots dt_n \right)^{\frac{1}{p}},
$$

$$
1 \leq p < \infty, \text{ for } h \in L^p[I^n],
$$

and

$$
\|h\|_{\infty} := \text{ess sup}_{t \in I^n} |h(t_1, t_2, \ldots, t_n)|, \text{ for } h \in L_{\infty}[I^n],
$$

where $t = (t_1, t_2, \ldots, t_n)$ and so $t_i \in [a_i, b_i], i = 1, 2, \ldots, n$.

The methodology of Cerone [5] is used for the current work. That work turns out to be a particular case of the three point development in Section 3 of the current paper. The generalised trapezoidal results of Section 2 are also specialisations of the three point results of Section 2.

2. Identities from an iterative approach and their bounds

The following theorem obtained by Cerone [5] uses an iterative approach to extend the Ostrowski functional identity to multidimensions. Firstly, we will require some notation.

Let $I^n = \prod_{i=1}^{n} [a_i, b_i] = [a_1, b_1] \times [a_2, b_2] \times \cdots \times [a_n, b_n]$. Further, let $f : I^n \to \mathbb{R}$ and define operators $F_i(f)$ and $\lambda_i(f)$ by

$$
F_i(f) := f(t_1, \ldots, t_{i-1}, x_i, t_{i+1}, \ldots, t_n) \text{ where } x_i \in [a_i, b_i]
$$

and

$$
\lambda_i(f) := \frac{1}{d_i} \int_{a_i}^{b_i} f(t_1, \ldots, t_{i-1}, t_i, t_{i+1}, \ldots, t_n) \, dt_i.
$$

That is, $F_i(f)$ evaluates $f(\cdot)$ in the $i$th variable at $x_i \in [a_i, b_i]$ and $\lambda_i(f)$ is the integral mean of $f(\cdot)$ in the $i$th variable. Assuming that $f(\cdot)$ is
absolutely continuous in the \( i \)th variable \( t_i \in [a_i, b_i] \), we have

\[
\mathcal{L}_i (f) = \frac{1}{d_i} \int_{a_i}^{b_i} p_i (x_i, t_i) \frac{\partial f}{\partial t_i} \, dt_i = (F_i - \lambda_i) (f),
\]

for \( i = 1, 2, \ldots, n \), where

\[
p_i (x_i, t_i) = \begin{cases} 
  \frac{t_i - a_i}{b_i - a_i}, & t_i \in [a_i, x_i] \\
  \frac{t_i - b_i}{b_i - a_i}, & t_i \in (x_i, b_i],
\end{cases}
\]

and \( d_i = b_i - a_i \).

Thus (2.3)-(2.4) is ostensibly equivalent to the Montgomery identity for \( f (t_1, \ldots, t_{i-1}, t_i, t_{i+1}, \ldots, t_n) \) absolutely continuous for \( t_i \in [a_i, b_i] \).

**Theorem 2.** Let \( f : I^n \to \mathbb{R} \) be absolutely continuous in such a manner that the partial derivatives of order one with respect to every variable exist. Then

\[
E_n (f) = f (x_1, x_2, \ldots, x_n) 
\]

\[
- \sum_{i=1}^{n} \frac{1}{d_i} \int_{a_i}^{b_i} f (x_1, x_2, \ldots, x_{i-1}, t_i, x_{i+1}, \ldots, x_n) \, dt_i 
\]

\[
+ \sum_{i<j} \frac{1}{d_i d_j} \int_{a_i}^{b_i} \int_{a_j}^{b_j} f (x_1, \ldots, x_{i-1}, t_i, x_{i+1}, \ldots, t_j, \ldots, x_n) \, dt_i \, dt_j 
\]

\[
- \cdots \cdots - \frac{(-1)^n}{D_n} \int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} f (t_1, \ldots, t_n) \, dt_1 \cdots dt_n
\]

\[
:= \tau_n \left( a, x, b \right),
\]

where

\[
E_n (f) = \frac{1}{D_n} \int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} \prod_{i=1}^{n} p_i (x_i, t_i) \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \, dt_1 \cdots dt_n,
\]

\( p_i (x_i, t_i) \) is given by (2.4), and

\[
D_n = \prod_{i=1}^{n} d_i, \quad d_i = b_i - a_i.
\]
Theorem 3. Let the conditions of Theorem 2 continue to hold. Then

\begin{equation}
D_n \left| \tau_n \left( a, x, b \right) \right| \leq \begin{cases} 
\prod_{i=1}^{n} P_i \left( 1 \right) \left\| \frac{\partial^n f}{\partial t_n \ldots \partial t_1} \right\|_{\infty}, & \frac{\partial^n f}{\partial t_n \ldots \partial t_1} \in L_\infty \left[ I^n \right] ; \\
\left( \prod_{i=1}^{n} P_i \left( q \right) \right)^{\frac{1}{q}} \left\| \frac{\partial^n f}{\partial t_n \ldots \partial t_1} \right\|_p, & \frac{\partial^n f}{\partial t_n \ldots \partial t_1} \in L_p \left[ I^n \right], \quad p > 1, \quad \frac{1}{p} + \frac{1}{q} = 1; \\
\prod_{i=1}^{n} \theta_i \left\| \frac{\partial^n f}{\partial t_n \ldots \partial t_1} \right\|_1, & \frac{\partial^n f}{\partial t_n \ldots \partial t_1} \in L_1 \left[ I^n \right], 
\end{cases}
\end{equation}

where \( \tau_n \left( a, x, b \right) \) is as defined by (2.5),

\begin{equation}
(q + 1) P_i \left( q \right) = (x_i - a_i)^{q+1} + (b_i - x_i)^{q+1},
\end{equation}

\begin{equation}
\theta_i = \frac{b_i - a_i}{2} + \left| x_i - \frac{a_i + b_i}{2} \right|.
\end{equation}

Remark 1. It was stated in Cerone [5] that the expression for \( \tau_n \left( a, x, b \right) \) may be written in a less explicit form which is perhaps more appealing. Namely,

\begin{equation}
\tau_n \left( a, x, b \right) = f \left( x_1, x_2, \ldots, x_n \right) + \sum_{k=1}^{n-1} \left( -1 \right)^k \sum \mathcal{M}_k + \left( -1 \right)^n \mathcal{M}_n,
\end{equation}

where \( \mathcal{M}_k \) represents the integral means in \( k \) variables with the remainder being evaluated at their respective interior point and \( \sum_k \mathcal{M}_k \) is a sum over all \( \binom{n}{k} \), \( k \)-dimensional integral means. Here

\[ \mathcal{M}_n = \frac{1}{D_n} \int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} f \left( t_1, \ldots, t_n \right) dt_1 \cdots dt_n \]
Multidimensional integration

\[
\sum_1^M_1 = \frac{1}{d_1} \int_{a_1}^{b_1} f(t_1, x_2, \ldots, x_n) \, dt_1 + \frac{1}{d_2} \int_{a_2}^{b_2} f(x_1, t_2, x_3, \ldots, x_n) \, dt_2 \\
+ \cdots + \frac{1}{d_n} \int_{a_n}^{b_n} f(x_1, x_2, \ldots, x_{n-1}, t_n) \, dt_n.
\]

It should be noted that (2.11) may be written as

\[
\tau_n(a, x, b) = \sum_{k=0}^{n} (-1)^k \sum_k M_k
\]

if we define the degenerate 0-th integral mean \( M_0 = f(x_1, x_2, \ldots, x_n) \).

The work of Cerone [3] used the Ostrowski functional (1.1) as a seed or generator for extension to higher dimensions using the Montgomery identity. We may prove, in an equivalent manner, utilising the generalised trapezoidal identity (1.7) with (1.2) as the generator of a higher dimensional result. We will restrict the current work to absolutely continuous functions so that the Riemann integral identity corresponding to (1.7) will be used. Let \( f : I^n \to \mathbb{R} \) and define the operator

\[
G_i(f) : = \frac{A_i}{d_i} f(t_1, \ldots, t_{i-1}, a_i, t_{i+1}, \ldots, t_n) \\
+ \frac{B_i}{d_i} f(t_1, \ldots, t_{i-1}, b_i, t_{i+1}, \ldots, t_n),
\]

where

\[
A_i = x_i - a_i, \quad B_i = b_i - x_i, \quad d_i = b_i - a_i.
\]

Here \( d_i G_i(f) \) represents the generalised trapezoid in the \( i \)-th variable giving the standard trapezoid when \( x_i = \frac{a_i + b_i}{2} \).

We note that \( A_i + B_i = d_i \) and if we extend the notation to

\[
\tilde{A}_i(x_i) = x_i - a_i, \quad \text{and} \quad \tilde{B}_i(x_i) = b_i - x_i,
\]

then we see that

\[
\tilde{A}_i(x_i) = \begin{cases} 0, & x_i = a_i \\ d_i, & x_i = b_i \end{cases} \quad \text{and} \quad \tilde{B}_i(x_i) = \begin{cases} d_i, & x_i = a_i \\ 0, & x_i = b_i. \end{cases}
\]
Now, for $f(\cdot)$ absolutely continuous in the $i^{th}$ variable $t_i \in [a_i, b_i]$ we have

$$M_i(f) = \frac{1}{d_i} \int_{a_i}^{b_i} q_i(x_i, t_i) \frac{\partial f}{\partial t_i} \, dt_i = (G_i - \lambda_i)(f), \quad i = 1, 2, \ldots, n,$$

where $G_i(f)$ and $\lambda_i(f)$ are as given by (2.13)-(2.14) and (2.2) respectively and,

$$q_i(x_i, t_i) \, d_i = \frac{t_i - x_i}{b_i - a_i}, \quad x_i, t_i \in [a_i, b_i].$$

Let $c^{(0)} = (c_1, c_2, \ldots, c_n)$, where $c_i = a_i$ or $b_i$ in the $i^{th}$ position for $i = 1, 2, \ldots, n$. Also, let $\sigma_0(c^{(0)})$ be the set of all such vectors which consists of $2^n$ possibilities. Further, let

$$\chi_k = \frac{n!}{\prod_{j=1}^{n} C_j d_j}, \quad k = 0, 1, \ldots, n,$$

where $C_j = A_j$ or $B_j$ with the exception that $k$ of the $C_j = d_j$ and so $C_j = 1$.

In a similar fashion, let $c^{(k)}$ be a vector taking on the fixed values $a_i$ or $b_i$ in the $j^{th}$ position except for $k$ of the positions which are variable, $t_i$. Let $M_k$ be $k$-dimensional integral means for $f(c^{(k)})$. Here $c^{(k)} \in \sigma_k(c^{(k)})$ the set of all such elements, of which there are $\binom{n}{k} 2^{n-k}$. With the above notation in place, the following theorem holds.

**Theorem 4.** Let $f : I^n \to \mathbb{R}$ be absolutely continuous and be such that all partial derivatives of order one in each of the variables exist. Then

$$R_n(f) = \sum_0 \chi_0 f(c^{(0)}) - \sum_1 \chi_1 M_1 + \sum_2 \chi_2 M_2 - \cdots - (-1)^{n-1} \sum_{n-1} \chi_{n-1} M_{n-1} + (-1)^n M_n$$

$$: = \rho_n(a, x, b),$$

where $\chi_k$ is as defined in (2.17), $M_k$ is the $k$-dimensional integral mean for $f(c^{(k)})$, specifically,

$$M_k = \frac{1}{D_k} \int_{a_1}^{b_1} \cdots \int_{a_n}^{b_n} f(t_1, t_2, \ldots, t_n) \, dt_1 \cdots dt_n$$

and $\sum_k$ is a sum involving each of the elements of $\sigma_k(c^{(k)})$ of which there are $\binom{n}{k} 2^{n-k}$. terms.
Further,

\[
R_n (f) = \frac{1}{D_n} \int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} \prod_{i=1}^{n} q_i (x_i, t_i) \frac{\partial^n f}{\partial t_n \cdots \partial t_1} dt_1 \cdots dt_n,
\]

and \( q_i (x_i, t_i) \) is given by (2.16), \( D_n \) by (2.7). Here, \( c_i \) is equal to either \( a_i \) or \( b_i \) in which case \( C_i = A_i \) or \( B_i \).

**Proof.** Let \( R_r (f) \) be defined by

\[
R_r (f) := \left( \prod_{i=1}^{r} M_i \right) (f),
\]

then from the left identity in (2.15), \( R_n (f) \) is as given by (2.19). Now,

\[
R_r (f) = M_r (R_{r-1} (f)), \quad \text{for} \quad r = 1, 2, \ldots, n,
\]

where \( R_0 (f) = f \).

Thus, from (2.20)

\[
R_1 (f) = M_1 (f) = (G_1 - \lambda_1) (f),
\]

which is the generalised trapezoidal identity for \( t_1, x_1 \in [a_1, b_1] \)

\[
R_1 (f) = \frac{1}{d_1} \int_{a_1}^{b_1} q_1 (x_1, t_1) \frac{\partial f}{\partial t_1} (t_1, t_2, \ldots, t_n) dt_1
\]

\[
= \frac{A_1}{d_1} f (a_1, t_2, \ldots, t_n) + \frac{B_1}{d_1} f (b_1, t_2, \ldots, t_n)
\]

\[
- \frac{1}{d_1} \int_{a_1}^{b_1} f (t_1, t_2, \ldots, t_n) dt_1
\]

contains three entities; two function evaluations and one integral. Further,

\[
R_2 (f) = M_2 (R_1 (f)) = (G_2 - \lambda_2) (R_1 (f))
\]

\[
= G_2 (R_1 (f)) - \lambda_2 (R_1 (f))
\]

\[
= \frac{A_2}{d_2} R_1 (f) \bigg|_{t_2 = a_2} + \frac{B_2}{d_2} R_1 (f) \bigg|_{t_2 = b_2} - \frac{1}{d_2} \int_{a_2}^{b_2} R_1 (f) dt_2
\]
contains nine entities. Thus,

\[
R_2(f) = \frac{A_2}{d_2}\left\{ \frac{A_1}{d_1} f(a_1, a_2, t_3, \ldots, t_n) + \frac{B_1}{d_1} f(b_1, a_2, t_3, \ldots, t_n) \right\} - \frac{1}{d_1} \int_{a_1}^{b_1} f(t_1, a_2, t_3, \ldots, t_n) dt_1 \right\} \\
+ \frac{B_2}{d_2}\left\{ \frac{A_1}{d_1} f(a_1, b_2, t_3, \ldots, t_n) + \frac{B_1}{d_1} f(b_1, b_2, t_3, \ldots, t_n) \right\} - \frac{1}{d_1} \int_{a_1}^{b_1} f(t_1, b_2, t_3, \ldots, t_n) dt_1 \right\} \\
- \frac{1}{d_2} \int_{a_2}^{b_2}\left\{ \frac{A_1}{d_1} f(a_1, t_2, \ldots, t_n) + \frac{B_1}{d_1} f(b_1, t_2, t_3, \ldots, t_n) \right\} - \frac{1}{d_1} \int_{a_1}^{b_1} f(t_1, t_2, \ldots, t_n) dt_1 \right\} dt_2.
\]

From the \(3^2\) entities of \(R_2(f)\) there are \(2^2\) function evaluations, \(2 \times 2\) single integrals and one double integral.

\[
R_3(f) = \mathcal{M}_3(R_2(f)) = (G_3 - \lambda_3)(R_2(f)) = G_3(R_2(f)) - \lambda_3(R_2(f))
\]

\[
= \frac{A_3}{d_3} R_2(f) \bigg|_{t_3=a_3} + \frac{B_3}{d_3} R_2(f) \bigg|_{t_3=b_3} - \frac{1}{d_3} \int_{a_3}^{b_3} R_2(f) dt_3.
\]
This will produce $3^2$ entities with $(\frac{1}{0})^2$ function evaluations, $(\frac{1}{0})^2$ single integrals, $(\frac{1}{2})^2$ double integrals and $(\frac{3}{0})^2$ triple integrals. The 2 occurs since evaluation is at either the $a_i$ or the $b_i$.

Continuing in this manner we obtain the result as stated where there are $3^n$ entities for $R_n(f)$, with $(\frac{1}{0})^n$ function evaluations only, $(\frac{n}{1})^n-1$ single integrals, $(\frac{n}{2})^{n-2}$ double integrals, ... , $(\frac{n}{n-1})^2$, $(n-1)^{th}$ integrals and one $n$-dimensional integral.

Corollary 1. Let the conditions of Theorem 4 continue to hold. Then

\begin{equation}
\hat{R}_n(f)
= \frac{1}{2^n} \sum_0^f \left( c^{(0)}_i \right) \cdot \frac{1}{2^{n-1}} \sum_1^M_1 \cdot \frac{(-1)^{n-1}}{2} \sum_{n-1}^M_{n-1} M_{n-1}
+ \frac{(-1)^n}{D_n} \int_{a_1}^{b_1} \cdots \int_{a_n}^{b_n} f(t_1, t_2, \ldots, t_n) dt_1 \cdots dt_n,
\end{equation}

where $c_i$ is either $a_i$ or $b_i$ for $i = 1, 2, \ldots, n$ and

\begin{equation}
\hat{R}_n(f) = \frac{1}{D_n} \int_{a_1}^{b_1} \cdots \int_{a_n}^{b_n} \prod_{i=1}^n q_i(\gamma_i, t_i) \frac{\partial^n f}{\partial t_1 \cdots \partial t_n} dt_1 \cdots dt_n,
\end{equation}

where $\gamma_i = \frac{a_i + b_i}{2}$.

Proof. The proof is obvious. On placing $x_i = \gamma_i = \frac{a_i + b_i}{2}$ we get $A_i = B_i = \frac{b_i - a_i}{2} = \frac{d_i}{2}$.

Remark 2. Taking $n = 1$ in (2.2) gives

\begin{equation}
\frac{1}{d_1} \int_{a_1}^{b_1} q_1(x_1, t_1) f'(t_1) dt_1
= \frac{A_1}{d_1} f(a_1) + \frac{B_1}{d_1} f(b_1) - \frac{1}{d_1} \int_{a_1}^{b_1} f(t_1) dt_1
\end{equation}

and so

\begin{equation}
\frac{1}{d_1} \int_{a_1}^{b_1} q_1 \left( \frac{a_1 + b_1}{2}, t_1 \right) f'(t_1) dt_1
= \frac{1}{2} \left[ f(a_1) + f(b_1) \right] - \frac{1}{d_1} \int_{a_1}^{b_1} f(t_1) dt_1,
\end{equation}

the trapezoidal identity involving the first derivative.
If \( n = 2 \), then from (2.23) and dropping the third to \( n \)th dimensions gives,

\[
R_2(f) = A_2 \cdot \frac{d_2}{d_1} \cdot f(a_1, a_2) + \frac{A_2}{d_2} \cdot B_1 \cdot \frac{d_1}{d_1} \cdot f(b_1, a_2) + \frac{B_2}{d_2} \cdot \frac{A_1}{d_1} \cdot f(a_1, b_2) + \frac{B_2}{d_2} \cdot \frac{B_1}{d_1} \cdot f(b_1, b_2)
\]

\[\text{(2.26)}\]

We now obtain bounds for \( \rho_n(a \sim, x \sim, b \sim) \) as defined in (2.18) for \( \partial^n f / \partial t^n \ldots \partial t_1 \in L_p[I^n], 1 \leq p \leq \infty \) should be with the usual Lebesgue norms.

**Theorem 5.** Let the conditions of Theorem 4 persist. Then,

\[
D_n \left| \rho_n(a \sim, x \sim, b \sim) \right| \leq \begin{cases} \prod_{i=1}^{n} Q_i(1) \left\| \frac{\partial^n f}{\partial t^n \ldots \partial t_1} \right\|_\infty, & \frac{\partial^n f}{\partial t^n \ldots \partial t_1} \in L_\infty[I^n]; \\ \left( \prod_{i=1}^{n} Q_i(q) \right)^{1/q} \left\| \frac{\partial^n f}{\partial t^n \ldots \partial t_1} \right\|_p, & \frac{\partial^n f}{\partial t^n \ldots \partial t_1} \in L_p[I^n], \ p > 1, \frac{1}{p} + \frac{1}{q} = 1 \\ \prod_{i=1}^{n} \phi_i \left\| \frac{\partial^n f}{\partial t^n \ldots \partial t_1} \right\|_1, & \frac{\partial^n f}{\partial t^n \ldots \partial t_1} \in L_1[I^n]; \end{cases}
\]

where \( \rho_n(a \sim, x \sim, b \sim) \) is as defined by (2.18),

\[
(2.28) \quad (q + 1) Q_i(q) = A_i^{q+1} + B_i^{q+1},
\]

\[
(2.29) \quad \phi_i = \frac{d_i}{2} + |x_i - \gamma_i|.
\]
Proof. From (2.18) and (2.19) we have

\begin{equation}
|\rho_n(a, x, b)| = |R_n(f)|
\end{equation}

\begin{align*}
\leq \frac{1}{D_n} \int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} \prod_{i=1}^{n} q_i(x_i, t_i) \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \ dt_1 \cdots dt_n.
\end{align*}

Now, for \(\frac{\partial^n f}{\partial t_n \cdots \partial t_1} \in L_\infty[I^n]\), then

\begin{align*}
|R_n(f)| & \leq \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_\infty \int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} \prod_{i=1}^{n} q_i(x_i, t_i) \ dt_1 \cdots dt_n \\
& = \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_\infty \prod_{i=1}^{n} \int_{a_i}^{b_i} |q_i(x_i, t_i)| dt_i \\
& = \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_\infty \prod_{i=1}^{n} \left[ \int_{a_i}^{x_i} (t_i - a_i) dt_i + \int_{x_i}^{b_i} (b_i - t_i) dt_i \right] \\
& = \frac{1}{2^n} \prod_{i=1}^{n} \left[ A_i^2 + B_i^2 \right] \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_\infty.
\end{align*}

Thus, combining (2.30) and (2.31) gives the first inequality in (2.27).

Further, using the Hölder inequality for multiple integrals, we have from (2.30) for \(\frac{\partial^n f}{\partial t_n \cdots \partial t_1} \in L_p[I^n], 1 < p < \infty\),

\begin{equation}
D_n |R_n(f)| \leq \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_p \left( \int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} \prod_{i=1}^{n} q_i(x_i, t_i) \ dt_1 \cdots dt_n \right)^{\frac{1}{q}}.
\end{equation}

Here, on using (2.16), we have

\begin{align*}
\int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} \prod_{i=1}^{n} q_i(x_i, t_i) \ dt_1 \cdots dt_n \\
= \prod_{i=1}^{n} \int_{a_i}^{b_i} |q_i(x_i, t_i)|^q dt_i
\end{align*}
\[
\prod_{i=1}^{n} \left[ \int_{a_i}^{x_i} (t_i - a_i)^q \, dt_i + \int_{x_i}^{b_i} (b_i - t_i)^q \, dt_i \right] = \frac{1}{(q + 1)^n} \prod_{i=1}^{n} \left[ A_i^{q+1} + B_i^{q+1} \right]
\]

and so the second inequality in (2.27) holds on utilising (2.30) and noting (2.28).

The final inequality in (2.27) is obtained from (2.31) for
\[
\partial_{n} f \in L_{1}[I^n]
\]
giving from (2.30)
\[
D_n |R_n(f)| \leq \sup_{t \in [a, b]} \prod_{i=1}^{n} q_i(x_i, t_i) \left\| \frac{\partial^n f}{\partial t_n \ldots \partial t_1} \right\|_1
\]
\[
= \prod_{i=1}^{n} \sup_{t_i \in [a_i, b_i]} |q_i(x_i, t_i)| \left\| \frac{\partial^n f}{\partial t_n \ldots \partial t_1} \right\|_1
\]
\[
= \prod_{i=1}^{n} \max \{A_i, B_i\} \left\| \frac{\partial^n f}{\partial t_n \ldots \partial t_1} \right\|_1.
\]

Noting that
\[
\max \{X, Y\} = \frac{X + Y}{2} + \frac{|X - Y|}{2}
\]
gives the final result.

**Remark 3.** It should be noted that the bounds given on \( \tau_n(a, x, b) \) by (2.8) are exactly the same bounds as those given by (2.27) for \( \rho_n(a, x, b) \). It was shown by Cerone [6] that the bounds in terms of the Lebesgue norms on \( |S(f; c, x, d)| \) and \( |T(f; c, x, d)| \), as defined in (1.1) and (1.2), are the same. Since the identities for these two functionals were used as *generators* for the multidimensional extension, the equality of the two sets of bounds (2.8) and (2.27) should not come as a great surprise. Finally we notice, due to convexity of the bounds in (2.27), that the sharpest bounds occur at \( x_i = \gamma_i = \frac{a_i + b_i}{2} \).
3. Three point identities and their bounds

For \( f(\cdot) \) absolutely continuous, then from (1.8)-(1.9)

\[
T(f; a, \alpha, x, \beta, b) = \int_a^b r(x, t) f'(t) \, dt,
\]

with

\[
r(x, t) = \begin{cases} 
  t - \alpha, & t \in [a, x] \\
  t - \beta, & t \in (x, b],
\end{cases}
\]

However, it may be noticed that

\[
T(f; a, \alpha, x, \beta, b) = T(f; a, \alpha, x) + T(f; x, \beta, b)
\]

and

\[
r(x, t) = \begin{cases} 
  q(\alpha, t), & t \in [a, x] \\
  q(\beta, t), & t \in (x, b],
\end{cases}
\]

where \( q(x, t) = \frac{t-x}{b-a}, t, x \in [a, b] \).

Thus we have the identity

\[
\Psi_n(a, \alpha, x, \beta, b) := \rho_n(a, \alpha, x) + \rho_n(x, \beta, b)
\]

\[
= \frac{1}{D_n} \int_{a_1}^{x_1} \cdots \int_{a_n}^{x_n} \left( t_i - \alpha_i \right) \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \, dt_1 \cdots dt_n
\]

\[
+ \frac{1}{D_n} \int_{x_1}^{b_1} \cdots \int_{x_n}^{b_n} \left( t_i - \beta_i \right) \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \, dt_1 \cdots dt_n
\]

\[
= \int_{a_1}^{b_1} \cdots \int_{a_n}^{b_n} \prod_{i=1}^{n} r_i(x_i, t_i) \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \, dt_1 \cdots dt_n,
\]

where

\[
r_i(x_i, t_i) = \begin{cases} 
  \frac{t_i - \alpha_i}{d_i}, & t_i \in [a_i, x_i] \\
  \frac{t_i - \beta_i}{d_i}, & t_i \in (x_i, b_i].
\end{cases}
\]
It is important to obtain an identity for the three point rule since the bounds are tighter than using the bounds of the two trapezoidal rules as this would entail using the triangle inequality. We notice that $\Psi_n\left(a, \alpha, x, \beta, b\right)$ in (3.5) is not expressed explicitly. This may be accomplished by returning to (2.18) or else we may use the generator methodology utilised to obtain the results in Section 2.

Let $f : I^n \rightarrow \mathbb{R}$ and define the operator

$$(3.7) \quad H_i(f) := \frac{\nu_i^{(a)}}{d_i} f(t_1, \ldots, t_{i-1}, a_i, t_{i+1}, \ldots, t_n) + \frac{\nu_i^{(x)}}{d_i} f(t_1, \ldots, t_{i-1}, x_i, t_{i+1}, \ldots, t_n) + \frac{\nu_i^{(b)}}{d_i} f(t_1, \ldots, t_{i-1}, b_i, t_{i+1}, \ldots, t_n),$$

where,

$$\nu_i^{(a)} = \alpha_i - a_i, \quad \nu_i^{(x)} = \beta_i - \alpha_i, \quad \nu_i^{(b)} = b_i - \beta_i, \quad d_i = b_i - a_i.$$  

Then, from (3.1)-(3.2) for $f(\cdot)$ absolutely continuous in the $i^{th}$ variable $t_i \in [a_i, b_i]$ we have

$$\tag{3.9} \mathfrak{M}_i(f) = \frac{1}{d_i} \int_{a_i}^{b_i} r_i(x_i, t_i) \frac{\partial f}{\partial t_i} dt_i = (H_i - \lambda_i)(f), \quad i = 1, 2, \ldots, n.$$ 

where $H_i(f)$ and $\lambda_i(f)$ are as given by (3.7)-(3.8) and (2.2) respectively.

If we now follow the work of the previous section and let $c^{(0)} = (c_1, c_2, \ldots, c_n)$, where now $c_i = a_i, x_i$ or $b_i$ in the $i^{th}$ partition for $i = 1, 2, \ldots, n$. Then $\sigma_0(c^{(0)})$ which is the set of all such vectors consists of $3^n$ possibilities. Further, let $\chi_n$ be as in (2.17) where now, $C_j = \nu_j^{(a)}$ or $\nu_j^{(x)}$ or $\nu_j^{(b)}$ are as defined by (3.8) with the exception that $k$ of the $C_j = d_j$ and so $C_j/d_j = 1$.

Further, $c^{(k)}$ is a vector taking on fixed values of either $a_i, x_i$ or $b_i$ in the $i^{th}$ position except for $k$ of the positions which are variable, $t_*$. Let $\mathcal{M}_k$ be $k$–dimensional integral means for $f(c^{(k)})$, then the following theorem holds.

**Theorem 6.** Let $f : I^n \rightarrow \mathbb{R}$ be absolutely continuous and be such that all partial derivatives of order one in each of the variables exist.
Then
\begin{equation}
B_n(f) = \sum_0 \chi_0 f(c^{(0)}) - \sum_1 \chi_1 \mathcal{M}_1 + \sum_2 \chi_2 \mathcal{M}_2 - \cdots - (-1)^{n-1} \sum_{n-1} \chi_{n-1} \mathcal{M}_{n-1} + (-1)^n \mathcal{M}_n
\end{equation}

\begin{equation}
= \Psi_n(a, \alpha, x, \beta, b),
\end{equation}

where
\begin{equation}
\chi_k = \prod_{j=1}^n \frac{C_j}{d_j}, \quad k = 0, 1, \ldots, n,
\end{equation}

with $C_j = \nu_j^{(a)}$, $\nu_j^{(x)}$ or $\nu_j^{(b)}$ as defined in (3.8) except for $k$ of the $C_j = d_j$ giving $\frac{C_j}{d_j} = 1$, $\mathcal{M}_k$ is the $k$-dimensional integral mean of $f(c^{(k)})$ and specifically,
\begin{equation}
\mathcal{M}_n = \frac{1}{D_n} \int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} f(c^{(n)}) \, dt_1 \cdots dt_n, \quad c^{(n)} = (t_1, t_2, \ldots, t_n).
\end{equation}

Finally, $\sum_k$ is a sum over all $\binom{n}{k}$ terms and $B_n(f)$ is as defined in (3.5).

\textbf{Proof.} Similar to that of Theorem 4 except that for each variable $t_i$ there are now three possible choices for evaluation of either $a_i$, $x_i$, or $b_i$.

The following theorem gives bounds for the $\Psi_n(a, \alpha, x, \beta, b)$ as given in either (3.10) or (3.5).

\textbf{THEOREM 7.} Let the conditions of Theorem 6 continue to hold. Then,
\begin{equation}
D_n \left| \Psi_n(a, \alpha, x, \beta, b) \right| \leq \begin{cases} 
\prod_{i=1}^n S_i (1) \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_\infty, & \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \in L_\infty[I^n]; \\
\left( \prod_{i=1}^n S_i(q) \right)^{\frac{1}{q}} \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_p, & \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \in L_\infty[I^n], \quad p > 1, \frac{1}{p} + \frac{1}{q} = 1 \\
\prod_{i=1}^n \zeta_i \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_1, & \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \in L_1[I^n]; 
\end{cases}
\end{equation}
where \( \|h\|_p \), \( 1 \leq p < \infty \) and \( \|h\|_{\infty} \) are defined by (1.11) and (1.12),
\[
\Psi_n \left( a, \alpha, x, \beta, b \right) \text{ is defined by (3.5) or, explicitly, by (3.10),}
\]
\[
(q + 1) S_i (q) = (\alpha_i - a_i)^{q+1} + (x_i - \alpha_i)^{q+1} + (\beta_i - x_i)^{q+1} + (b_i - \beta_i)^{q+1},
\]
\[
(3.14) \ 
\zeta_i = \frac{1}{2} \left\{ \frac{b_i - a_i}{2} + \left| \alpha_i - \frac{a_i + x_i}{2} \right| + \left| \beta_i - \frac{x_i + b_i}{2} \right| + \left| x_i - \frac{a_i + b_i}{2} \right| + \left| \alpha_i - \frac{a_i + x_i}{2} \right| - \left| \beta_i - \frac{x_i + b_i}{2} \right| \right\}.
\]

**Proof.** From (3.10) and (3.5)
\[
\left| \Psi_n \left( a, \alpha, x, \beta, b \right) \right| = \left| B_n (f) \right| \leq \frac{1}{D_n} \int_{a_1}^{b_1} \cdots \int_{a_n}^{b_n} \prod_{i=1}^{n} r_i (x_i, t_i) \left| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right| dt_1 \cdots dt_n.
\]
Now, for \( \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \in L_\infty [I^n] \) then
\[
(3.16) \ 
D_n \left| B_n (f) \right| \leq \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_\infty \int_{a_1}^{b_1} \cdots \int_{a_n}^{b_n} \prod_{i=1}^{n} r_i (x_i, t_i) \right| dt_1 \cdots dt_n,
\]
where \( \|h\|_{\infty} \) is defined by (1.12).
Here
\[
\int_{a_1}^{b_1} \cdots \int_{a_n}^{b_1} \left| \prod_{i=1}^{n} r_i (x_i, t_i) \right| dt_1 \cdots dt_n = \prod_{i=1}^{n} \int_{a_i}^{b_i} \left| r_i (x_i, t_i) \right| dt_i,
\]
and where
\[
\int_{a_i}^{b_i} \left| r_i (x_i, t_i) \right| dt_i
\]
\[
= \int_{a_i}^{\alpha_i} \left( \alpha_i - t_i \right) dt_i + \int_{\alpha_i}^{x_i} \left( t_i - \alpha_i \right) dt_i
\]
\[
+ \int_{x_i}^{\beta_i} \left( \beta_i - t_i \right) dt_i + \int_{\beta_i}^{b_i} \left( t_i - \beta_i \right) dt_i
\]
\[
= \frac{1}{2} \left[ (\alpha_i - a_i)^2 + (x_i - \alpha_i)^2 + (\beta_i - x_i)^2 + (b_i - \beta_i)^2 \right].
\]
Substitution of the above results into (3.16) gives the first inequality in (3.12) with $S_i(1)$ given from (3.13).

Moreover, using the Hölder inequality for multiple integrals we have, from (3.15) for $\frac{\partial^n f}{\partial t_n \cdots \partial t_1} \in L_p [I^n], \ 1 < p < \infty$,

\[(3.17)\]

\[D_n | B_n(f) | \leq \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_p \left( \int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} \left| \prod_{i=1}^{n} r_i(x_i, t_i) \right|^q dt_1 \cdots dt_n \right)^{\frac{1}{q}},\]

where

\[
\int_{a_n}^{b_n} \cdots \int_{a_1}^{b_1} \left| \prod_{i=1}^{n} r_i(x_i, t_i) \right|^q dt_1 \cdots dt_n
\]

\[= \prod_{i=1}^{n} \int_{a_i}^{b_i} |p_i(x_i, t_i)|^q dt
\]

\[= \prod_{i=1}^{n} \left\{ \int_{a_i}^{a_i} (\alpha_i - t_i)^q dt_i + \int_{a_i}^{x_i} (t_i - \alpha_i)^q dt_i + \int_{x_i}^{\beta_i} (\beta_i - t_i)^q dt_i + \int_{\beta_i}^{b_i} (t_i - \beta_i)^q dt_i \right\}
\]

\[= \frac{1}{(q+1)^n} \prod_{i=1}^{n} \left[ (\alpha_i - a_i)^{q+1} + (x_i - \alpha_i)^{q+1} + (\beta_i - x_i)^{q+1} + (b_i - \beta_i)^{q+1} \right].\]

Substitution of the above calculations into (3.17) gives the second inequality in (3.12) with $S_i(q)$ as given by (3.13).

Finally, for $\frac{\partial^n f}{\partial t_n \cdots \partial t_1} \in L_1 [I^n]$ we have from (3.15)

\[D_n | B_n(f) |
\]

\[\leq \sup_{t \in [a_b]} \left| r_i(x_i, t_i) \right| \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_1
\]

\[= \prod_{i=1}^{n} \sup_{t \in [a_i, b_i]} |r_i(x_i, t_i)| \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_1
\]

\[= \prod_{i=1}^{n} \max \left\{ \alpha_i - a_i, x_i - \alpha_i, \beta_i - x_i, b_i - \beta_i \right\} \left\| \frac{\partial^n f}{\partial t_n \cdots \partial t_1} \right\|_1.
\]
Using the result that
\[
\max \{X, Y\} = \frac{X + Y}{2} + \frac{|X - Y|}{2}
\]
twice produces the final inequality in (3.12).

Remark 4. The bounds obtained above in Theorem 7 are the product of the bounds for the one dimensional integral results. These were studied extensively in Cerone and Dragomir [8]. It should further be noted that the three point results of the current section recaptures the generalised trapezoidal results of the previous section if we take \(\alpha_i = \beta_i = x_i\). In addition, the Ostrowski type results of Cerone [5] are recaptured if we take \(\alpha_i = a_i\) and \(\beta_i = b_i\).

If we take \(n = 2\) then the results of Hanna et al. [18] are recaptured. Chapter 6 by Hanna in [15] treats double integrals while in Chapter 5 of the same book, Barnett et al. produce related but different results for multiple integrals involving only evaluation at an interior point.

Finally, we notice that the best choice of the \(\alpha_i, \beta_i\) and the \(x_i\) in (3.12) is at their respective midpoints, providing the sharpest bound. That is, \(\alpha_i = \frac{a_i + x_i}{2}, \beta_i = \frac{x_i + b_i}{2}\) and \(x_i = \frac{a_i + b_i}{2}, i = 1, 2, \ldots, n\).

4. Concluding remarks

Perturbed rules using the Chebychey functional as determined by Cerone [5] for multiple integrals obtained using an Ostrowski functional as a generator can also be produced here for both the trapezoidal and three point developments. This, however, will not be pursued further here. The procedure developed in [5] and extended here may also be used to include higher order formulae involving the behaviour of higher derivatives for its bounds. Multidimensional results based on an \(m\) branched Peano kernel producing function evaluations at \(m + 1\) points are also possible using the methodology demonstrated in Section 3 for \(m = 2\). Finally, weighted rules are also possible using a weighted functional as a generator, however, this may be restricted to product form weight functions in the multidimensional result. These will also not be investigated further here.

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