

The cell boundary element methods

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Abstract

We consider the model second-order elliptic problem:

$$\begin{aligned} -\nabla \cdot K \nabla u &= f \quad \text{in } \Omega, \\ u &= 0 \quad \text{on } \partial\Omega, \end{aligned}$$

where Ω is a bounded polygonal domain in \mathbb{R}^2 . Assume that Ω is composed of disjoint polygonal subdomains $\Omega_1, \dots, \Omega_J$ and that K is a function such that $0 < K_* \leq K(x) \leq K^* < \infty$ and $K(x) = K_j$ in Ω_j for each j .

The localized problem becomes

$$\begin{aligned} -K_T \Delta u &= f \quad \text{in } T, \\ \left[K \frac{\partial u}{\partial \nu} \right] &:\equiv K_T \frac{\partial u}{\partial \nu} + K_{T'} \frac{\partial u'}{\partial \nu'} = 0 \quad \text{on } e_p = \partial T \cap \partial T'. \end{aligned}$$

The continuity of the flux can be weakened as follows:

$$\int_{e_p} \left[K \frac{\partial u}{\partial \nu} \right] = 0$$

and this is the motivation of the CBE method. Introduce F_T , a particular solution of (0.1) so that

$$F_T(x) = \frac{1}{K_T} \int_T \Gamma(x-y) f(y) dy, \quad x \in T,$$

where $\Gamma(x) = -\frac{1}{2\pi} \log|x|$ is the fundamental solution of $-\Delta$. Then u admits the following decomposition:

$$u = v + (F - H(F)) \quad \text{on } T,$$

where $\Delta v = 0$ and $u = v$ on ∂T . $F - H(F)$ is a bubble function.

Our nonconforming CBE method is to find $v_h \in V_{0,h}$ such that

$$\int_{e_p} \left[K \frac{\partial v_h}{\partial \nu} \right] ds = \int_{e_p} \left[K \left(\frac{\partial H_h(F)}{\partial \nu} - \frac{\partial F}{\partial \nu} \right) \right] ds \quad \text{for all } p \in \mathcal{V}_h^i.$$

Here, H_h is the harmonic interpolation. Then $u_h = v_h + (F - H_h(F))$ is the solution we are looking for.

The advantage of the CBE method is that

- The flux conservation holds as the finite volume method

- The cost for mesh generation is the same as that of the finite element method

Numerical Experiments

The computational domain is taken as the unit square $\bar{\Omega} := [0, 1] \times [0, 1]$ and a quasi-uniform mesh: the vertices are given as

$$x_i = \frac{2t_i}{1+t_i} \quad \text{and} \quad y_j = \frac{1.5t_j}{1+.5t_j}, \quad 0 \leq i, j \leq n,$$

where $\{t_j = j/n, j = 0, \dots, n\}$ and the triangular mesh is then generated by bisecting each rectangle by the diagonal line from the top right to the bottom left.

Example 1. We consider the following Poisson equation:

$$\begin{aligned} -\Delta u &= -4 - 6x \quad \text{in } \Omega, \\ u &= g \quad \text{on } \partial\Omega, \end{aligned}$$

where the function g is chosen so that the exact solution is $u(x, y) = e^x \cos(y) + x^2 + y^2 + x^3$. Then the total flux on $D = [0, 2/3] \times [0, 3/5]$ is 2.4.

n^2	$\ u - u_h\ _{0,h}$	α	$\ \nabla u - \nabla u_h\ _{0,h}$	α	flux
5^2	7.0473e-3		6.3160e-1		
10^2	2.0732e-3	1.7652	3.2263e-1	0.9691	2.4
20^2	5.4437e-4	1.9292	1.6256e-1	0.9889	2.4
40^2	1.3817e-4	1.9781	8.1498e-2	0.9961	2.4

Table 1: Numerical results for the P_1 nonconforming method

n^2	$\ u - u_h\ _{0,h}$	α	$\ \nabla u - \nabla u_h\ _{0,h}$	α	flux
5^2	1.0365e-4		8.9443e-3		
10^2	3.4297e-5	1.5956	2.2992e-3	1.9599	2.4 + 1.57e-4
20^2	9.1723e-6	1.9027	5.7823e-4	1.9914	2.4 + 1.32e-8
40^2	2.3202e-6	1.9830	1.4464e-4	1.9992	2.4 + ϵ

Table 2: Numerical results for the $P_{2+1/2}$ -method

n^2	$\ u - u_h\ _{0,h}$	α	$\ \nabla u - \nabla u_h\ _{0,h}$	α	flux
5^2	1.5516e-4		9.0081e-3		
10^2	4.5665e-5	1.7646	2.3189e-3	1.9578	2.4
20^2	1.1795e-5	1.9530	5.8307e-4	1.9917	2.4
40^2	2.9673e-6	1.9909	1.4587e-4	1.9990	2.4

Table 3: Numerical results for the modified $P_{2+1/2}$ -method

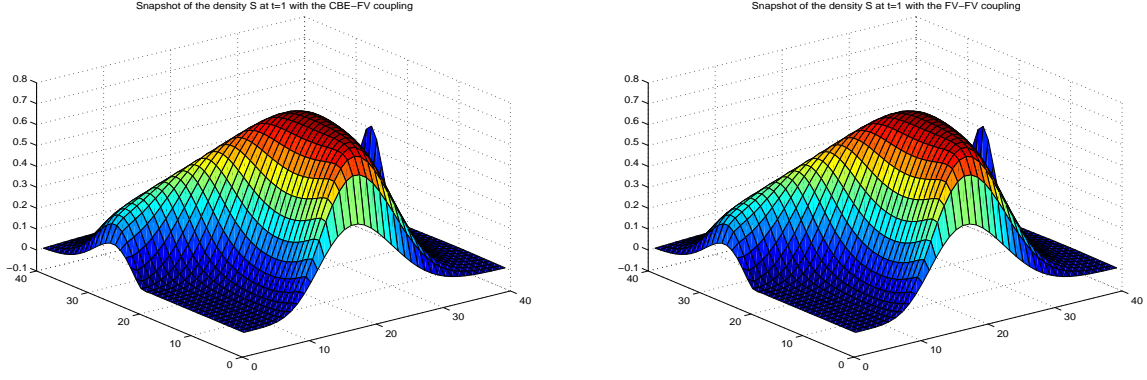


Figure 1: Snapshots of S at $t = 1$ for the P_1 CBE-FV method and FV-FV couplings, respectively

n^2	$\ u - u_h\ _{\infty, h}$	α	$\ \nabla u - \nabla u_h\ _{0, h}$	α
5^2	1.5989e-005		6.8047e-3	
10^2	1.2601e-006	3.6654	1.7463e-3	1.9622
20^2	9.6459e-008	3.7075	4.4266e-4	1.9800
40^2	6.9356e-009	3.7978	1.1146e-4	1.9897

Table 4: Numerical results for the $P_{2+1/2}$ -method on the square mesh

Example 2. We consider a subsurface flow problem.

$$\begin{aligned} \Delta u &= 1 \quad \text{in } \Omega, \\ \frac{\partial S}{\partial t} &= -\sigma \cdot \nabla S + 0.01 \Delta S \quad \text{in } \Omega, \end{aligned}$$

where $\sigma = -\nabla u$. The boundary condition for u is given as follows:

$$\begin{cases} \frac{\partial u}{\partial \nu} = -1 & \text{on } \{x_1 = 0, 0 < x_2 < 1/2\}, \\ \frac{\partial u}{\partial \nu} = 2 & \text{on } \{x_1 = 1, 1/2 < x_2 < 1\}, \\ u = 0, & \text{elsewhere.} \end{cases}$$

The initial and boundary conditions for S are as follows:

$$S(x, 0) = \begin{cases} 1, & x \in (0, 1/2) \times (0, 1/2), \\ 0, & \text{elsewhere,} \end{cases} \quad \text{and} \quad S(x, t) = 0, \quad x \in \partial\Omega.$$

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